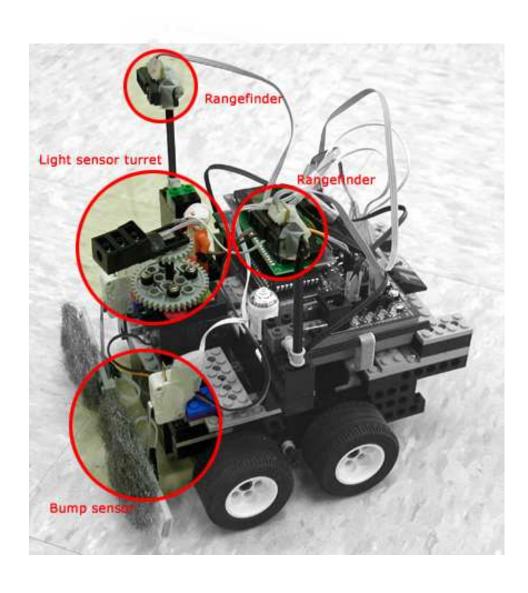


Project 2:

Group 10: Amit Maole, Brent Eskridge Klo Utley, Tony Lopez



Hardware





Robot system

Sensor sweep

Strategic behaviors

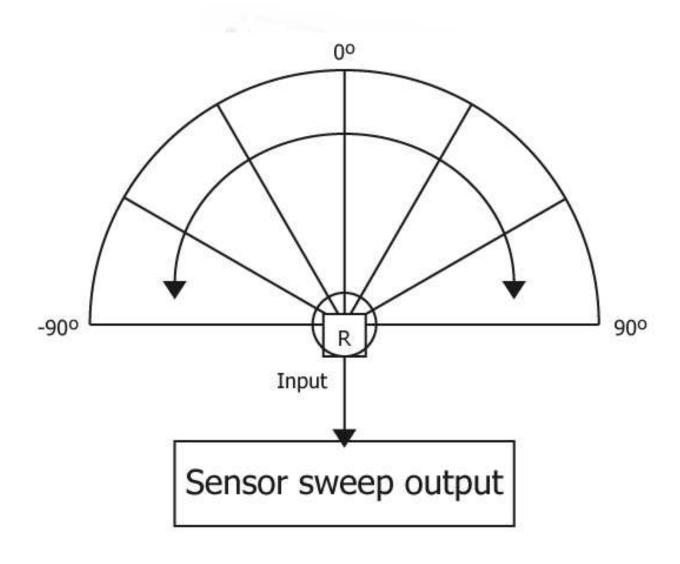
Tactical behaviors

Motor control

SFX Architecture

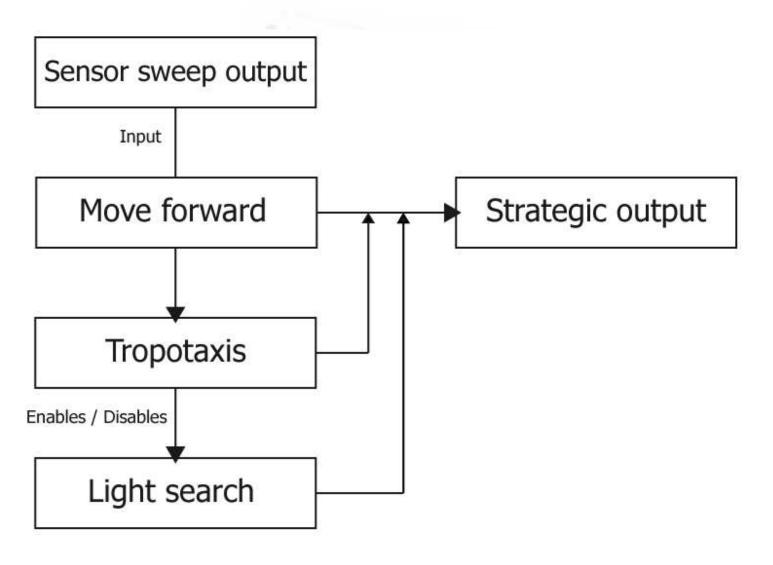


Sensor Sweep



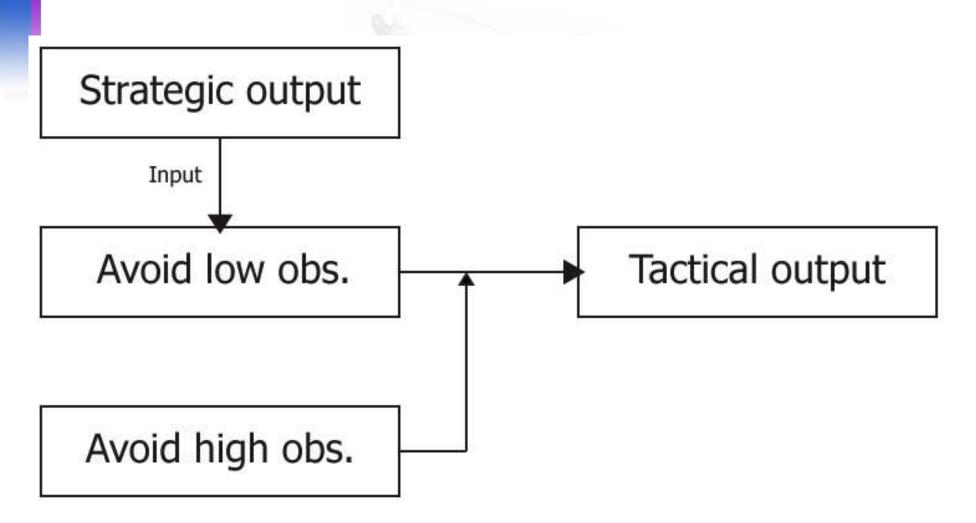


Strategic Behaviors





Tactical Behaviors





Software Lessons Learned

- The frequency of turns in the light search behavior was too high.
- Simplicity in design is more important than flexibility in design.
- Adding a certain amount of randomness can eliminate some cyclic behavior, but it is still easy to get into such a situation. Fixing it adds quite a bit of complexity to the design, which can introduce other problems.



Demo Results

- Demo 1 0 Lights
- Demo 2 1 Light
- Demo 3 2 Lights, Bucket, 1 Light
- Demo 4 3 Lights