

## Presentation Outline...

1. Hello
2. Introduce Self...
3. Prototype Philosophy (Save Time)
4. Hardware...
  - Basic Design
  - Motor To Wheel Gear Ratio: 1:15
  - Radar
  - Steering
  - Sensors...
5. Software...
  - Behavior Only.
  - Tweaked a lot...
  - Sensory Input Time vs. Speed...