

Digital to Analog and Back

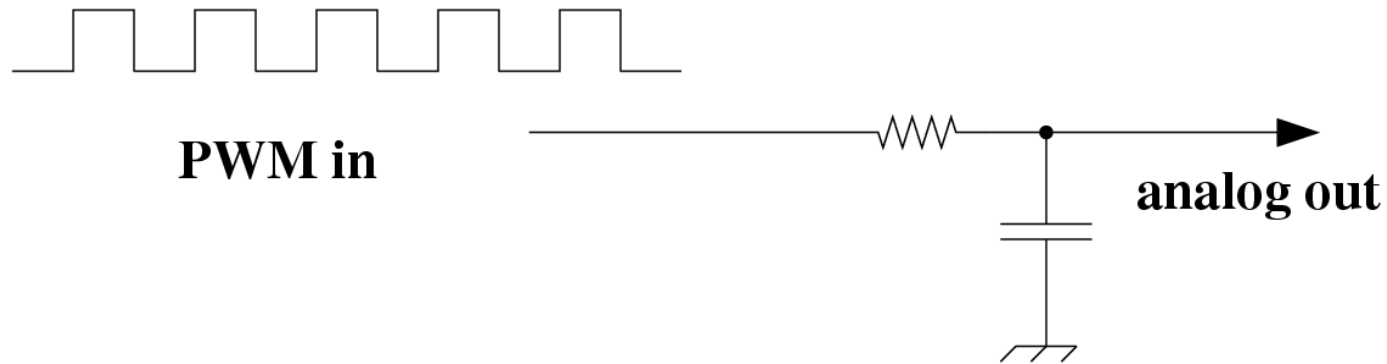
- Analog: encoding information using voltage
 - Many sensors use voltage as an output
 - Motors torque is determined by current passing through the motor
- Digital: encoding information with bits

How to move between these?

Digital to Analog Conversion

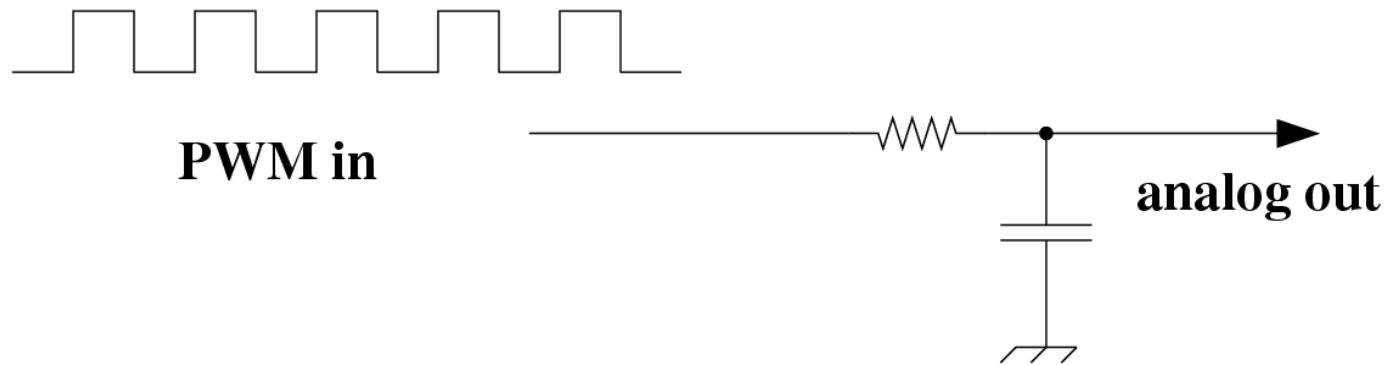
How could we do this with a single digital pin of our microprocessor?

Digital to Analog Conversion: Pulse Width Modulation



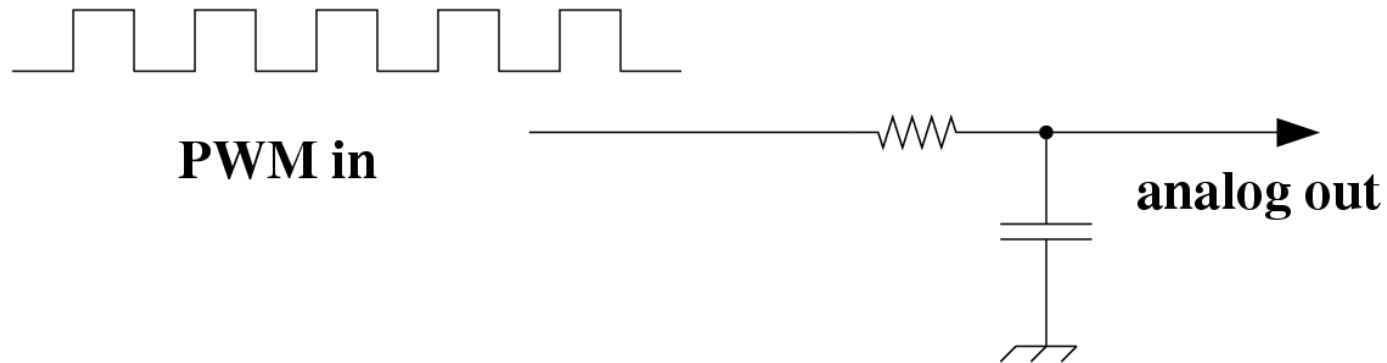
What does this circuit do?

Digital to Analog Conversion: Pulse Width Modulation



- Processor digital pin: generate PWM signal
- RC circuit “smooths” this PWM signal out
- Pulse width determines smoothed voltage

D2A: Pulse Width Modulation



- Easy to implement
- But:
 - Assumes “analog out” requires zero current
 - Smoothed signal may not be smoothed enough
 - Filter induces a delay

Digital to Analog Conversion: Resistive Network

Sometimes need faster response

- Solution: use multiple digital pins
- What would this circuit look like?

Analog to Digital Conversion

For a given voltage, what is the digital representation of the voltage?

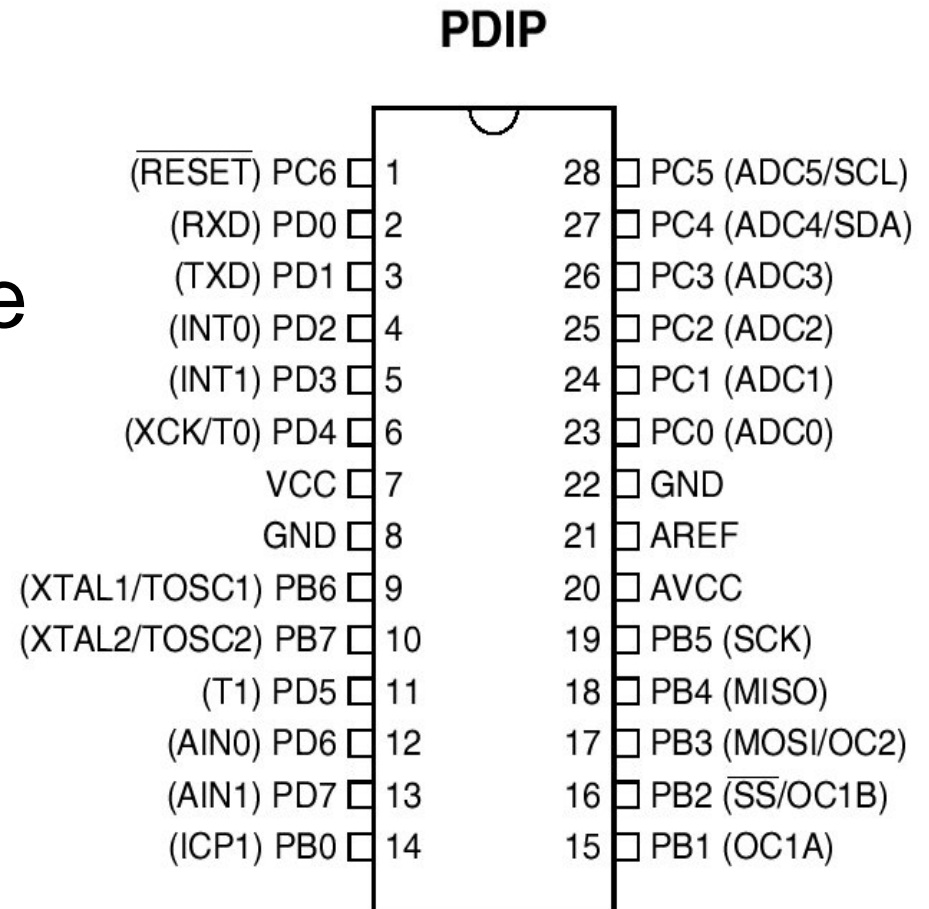
- How would we implement this?

Analog to Digital Conversion

- For a given voltage, what is the digital representation of the voltage?
- Common approach: successive approximation
 - Use a D2A converter to produce a voltage V
 - Compare this with the input voltage V_i
 - If different, then increase/decrease V
 - Repeat (stopping when V is close to V_i)

A2D in the Mega8

- The mega8 contains hardware that implements successive approximation
- 5 mega8 pins can be configured as analog input pins



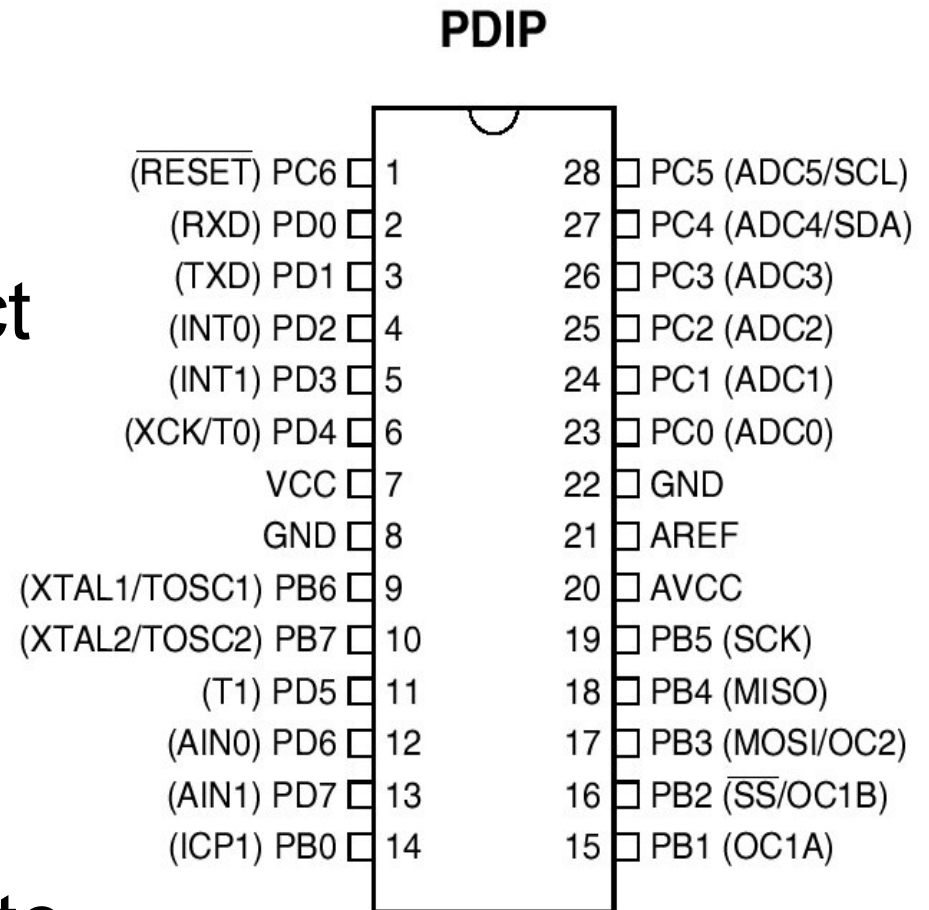
A2D in the Mega8

AVCC: connect to +5V

AREF: (optional) connect to +5V

- Measuring voltages between 0 and +5V

Connect input analog signal to the appropriate ADC pin



A Code Example

```
// Initialize adc
adc_set_reference(ADC_REF_AREF);           // Use the AREF reference pin
adc_set_adlar(0);                          // For our purposes, always use 0
adc_set_prescalar(ADC_PRESCALAR_128);     // Necessary with 16MHz clock
                                           // and 10 bit resolution

// Turn on ADC Converter
adc_set_enable(ADC_ENABLE);

      :
      :
long val;

// Can do the following an arbitrary number of times

adc_set_channel(ADC_CHANNEL_0);           // ADC0
// Actually start a conversion
adc_start_conversion();

<Could go off and do something else for a while>

val = adc_read(); // Read the analog value
```

Analog Conversion Notes

- All functions are provided in oulib
- See oulib.h for the definition of constants
- Can get to the example code from the Atmel HowTo
www.cs.ou.edu/~fagg/classes/general/atmel

Analog Conversion Notes

- Setting the maximum voltage:

```
adc_set_reference(ADC_REF_AREF);           // Use the AREF reference pin
```

- Can also used a fixed voltage (+2.56V):

```
adc_set_reference(ADC_REF_2p56V);
```

Analog Conversion Notes

- Determining how fast the conversion requires:

```
adc_set_prescalar(ADC_PRESCALAR_128); // Necessary with 16MHz clock  
                                         // and 10 bit resolution
```

- Conversion requires:

$128 * 15 / 16000000$ seconds

- Can convert faster, but may not get the full 10-bit resolution

Analog Conversion Notes

- Reading out the value:

```
val = adc_read();           // Read the analog value
```

- Blocks until conversion is complete
- Will return a value between 0 and 0x3FF (1023)
- Thread safe

Analog Conversion Notes

- Can configure the mega8 to interrupt on conversion completion

Other Devices

- External devices are available that will perform D2A and A2D
- Often interface to the microprocessor via I²C or SPI
 - (these are high-speed serial protocols)
- Many options
 - Resolution
 - Conversion speed
 - Number of channels