CS 2334: Project 5 Java Graphics

Project 4 Lessons

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- Get layout working first, then interaction
- May not have anything selected by a JList at a given instant in time: code must be robust to this
- Tracking down Exceptions in "tall" stack traces

Project 5

Animate the infant:

- Show top, side and rear view of the infant
- Allow user to select time instant to be displayed
- Animation using Timers

• Demonstration

Objectives

Create a Graphical User Interface for Animation

- Create a tree data structure for representing a kinematic tree
- Create a class for flexibly transforming 3D data into a 2D picture
- Use JSliders to accept input
- Use Timers to create animations
- Continue to exercise good coding practices for Javadoc and for testingDrop-down menus (JMenuBar)

Kinematic Tree

Representation of a biological or robot body. In our case:

- Rigid links connected by rotational joints
- Root point: base of the tree
 - For us: center point between hips



Sanini et al., 2015

Kinematic Tree

A single point can branch along multiple paths

- In this figure: the root point branches in three directions:
 - Left hip
 - Right hip
 - Point between the shoulder blades (the back)

We refer to these as the **children** of the root point



Sanini et al., 2015

Drawing a Kinematic Tree

Assume that we know the locations of all of the points

- 1. Start at the root point
- 2. For each child point:
 - 1. Draw a line from this point to the child
 - 2. Recursively draw the child



Sanini et al., 2015

Infant Model

- Our data structure contains most of the points we need within a single State
 - Back, shoulders, elbows, wrists, ...
- Some points are not defined, but they are fixed
 - Location of the hip sockets
 - Location of the small of the back



Rendering

We are not working in 3D, here. Instead: we are creating simple 2D projections

- Top view: Map X to screen X and Y to screen Y (flipped)
- Side view: Map X to screen X and Z to screen Y (flipped)
- Rear view: Map Y to screen X (flipped) and Z to screen Y (flipped)

Scaling: we must also translate from meters to pixels

KinematicPoint

A KinematicPoint must be able to:

- Describe the location of some specified dimension (subfield)
- Given subfields for each of the screen X and screen Y dimensions, draw the point and its children



Drawing a Single KinematicPointAbstract

- Extract the GeneralValue for the screen X and screen Y subfields
- For each child:
 - Extract the GeneralValue for the screen X and screen Y subfields
 - If all GeneralValues are valid, then draw a line from this point to the child point (specifically, we are drawing a BasicStroke)
 - Draw the child

KinematicPanel

JPanel that renders a single view of the kinematic model

- Maps from 3D point to 2D screen coordinates
- Scale translates from real coordinates (meters) to pixels
- In some cases, flips the sign of the pixel coordinates



Graphical User Interface

- Menu is the same
- Selection of week only
- DataPanel:
 - Three different views
 - Textual information
 - Control of time step to render



Deadlines

- Project must be submitted by Friday, Dec 1st @6:00pm
- Code review must be completed by Friday, Dec 8th
 - This is an absolute deadline